

# Real-time Likelihood Map Generation to Localize Short-duration Gamma-ray Transients

Jeremy Buhler and Marion Sudvarg  
Washington U. in St. Louis  
{jbuhler, msudvarg}@wustl.edu

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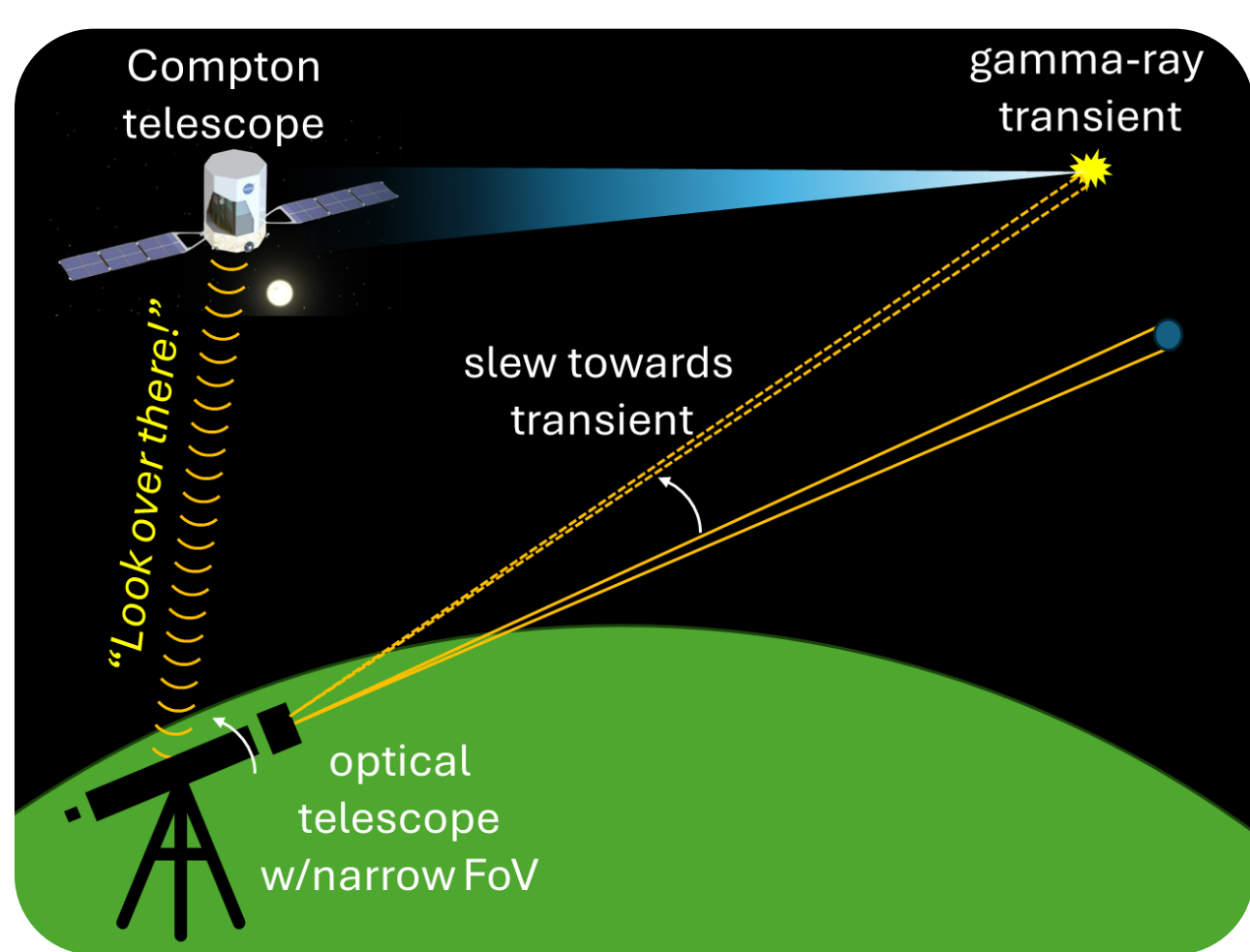


High-energy transient astrophysical phenomena, such as supernovae and binary neutron star mergers, benefit from a multi-wavelength investigation in which a space- or balloon-based omnidirectional telescope detects and localizes early high-energy emissions (e.g., a gamma-ray burst), then alerts a narrow-field-of-view follow-up instrument to observe the source. The high-energy telescope must provide a map that assigns to each sky location a likelihood that the source appears there. To issue prompt alerts despite limits on communication bandwidth and latency, it is desirable to compute these maps aboard the high-energy telescope, but doing so requires computing under stringent size, weight, and power constraints.

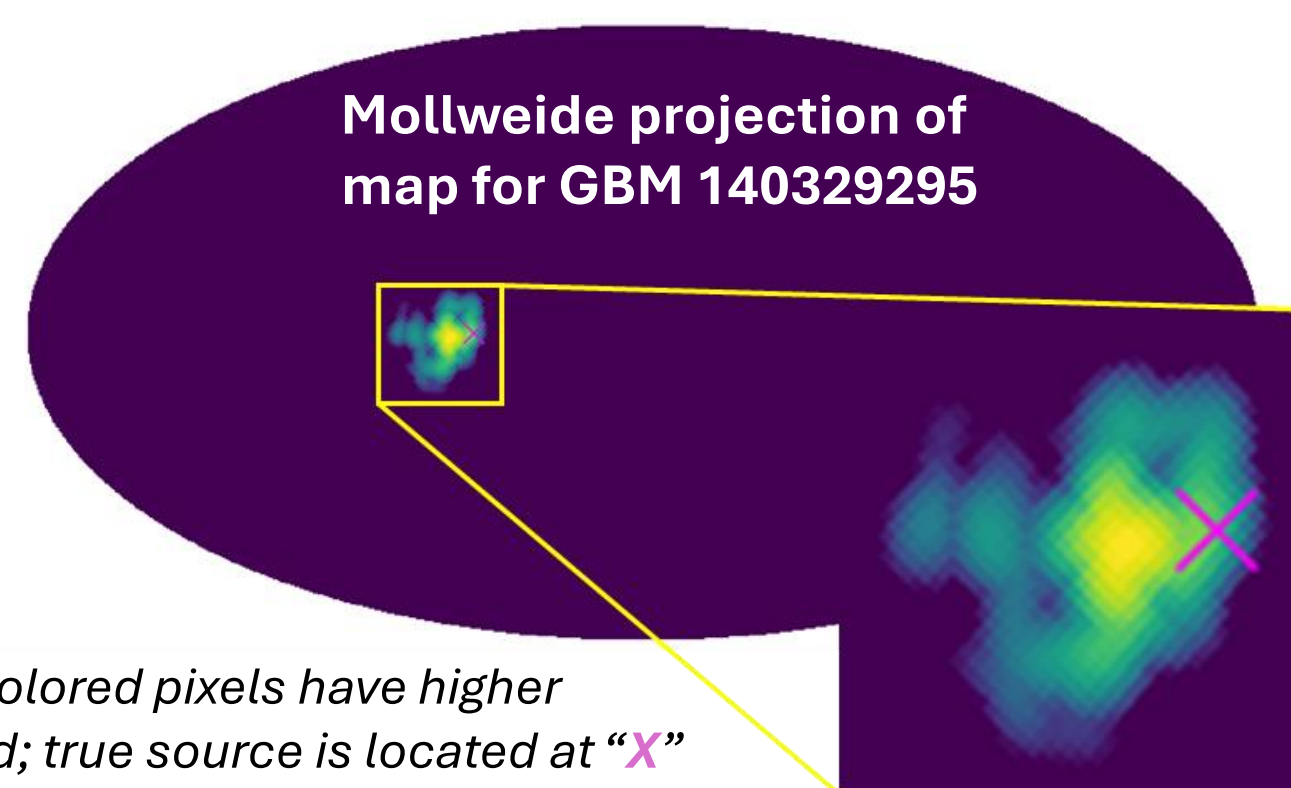
This work describes a real-time likelihood mapping implementation for Compton telescopes that is suitable for on-board computation. We use an adaptive multi-resolution approach and exploit data-reduction and parallelization opportunities to achieve sub-second construction of high-resolution maps (HEALPix  $N_{\text{side}}=64$ ) using a detailed instrument response matrix on a low-power ( $< 10$  W) embedded computing platform. We validate the speed and accuracy of our mapping approach on simulated gamma-ray transients from the third COSI Data Challenge [1].

## The Task

- Compton telescope detects transient gamma-ray point source (e.g., GRB)
- Must **localize** source in the sky...
- ... and **alert** cooperating telescope with narrow FoV to point towards it.



Uncertainty in direction  $\vec{s}$  to source is expressed by **likelihood map** that scores each possible direction



Lighter-colored pixels have higher likelihood; true source is located at "X"

## Challenge

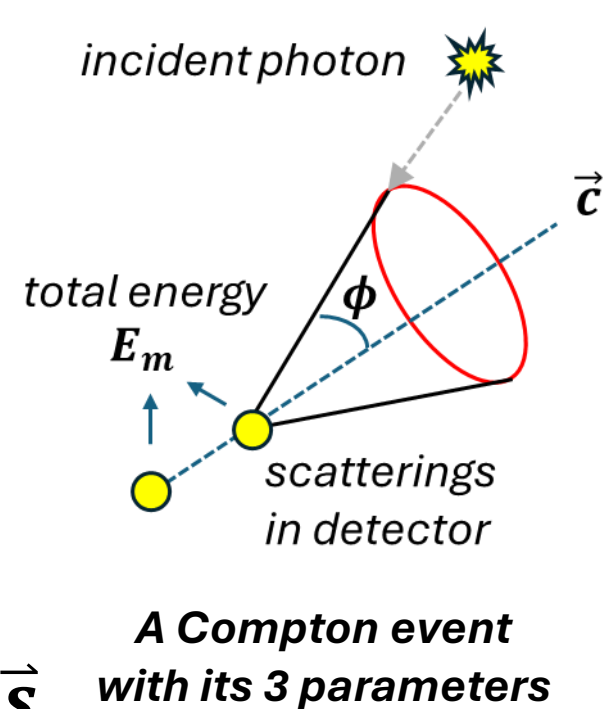
Provide actionable alerts to partner instrument **ASAP!**

Can we compute accurate likelihood map **quickly** ( $\leq 1$ s) and at **high resolution** ( $\sim 1^\circ$ )?

- To avoid latency and bandwidth limits of terrestrial computation, **compute maps in real time aboard Compton telescope**.
- Must operate with **low-power on-board hardware**.

## Mapping Computation

- Given set  $D$  of **Compton events** ( $E_m, \phi, \vec{c}$ ) produced by mix of **source photons** and **background radiation**
- For **each** possible source direction  $\vec{s}$ , compute **log likelihood ratio (LLR)** of **two hypotheses** given  $D$ :
  - $H_S - D$  arises from mix of source at  $\vec{s}$  and background
  - $H_B - D$  arises from background only



A Compton event with its 3 parameters

LLR calculation requires two probabilistic models:

**Instrument Response**  $R[\vec{s}, E_i, E_m, \phi, \vec{c}]$

defines  $\Pr(E_m, \phi, \vec{c})$  for source photons from  $\vec{s}$  with energy  $E_i$

**Background**  $B[E_m, \phi, \vec{c}]$

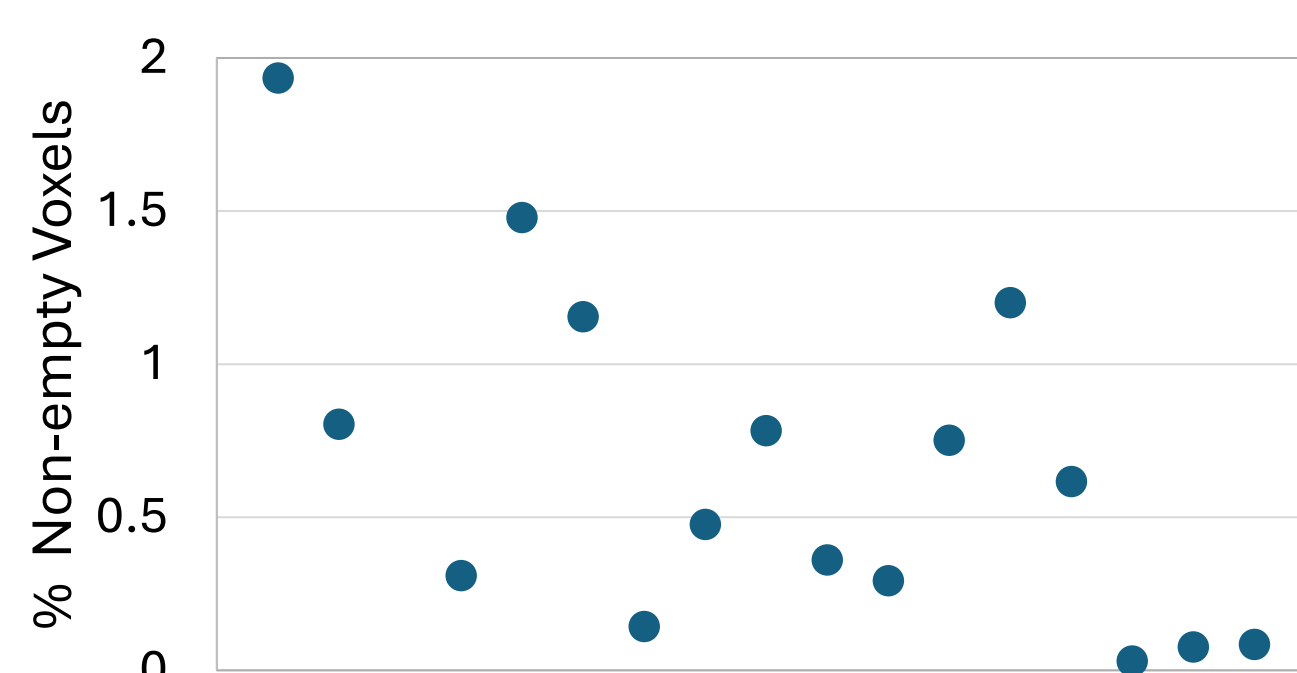
defines  $\Pr(E_m, \phi, \vec{c})$  for background particles

Our LLR calculation follows binned Poisson approach with source intensity fitting from `cosipy` library [3].

## Strategies for High Performance

### 1. Problem Size Reduction

- Space of possible ( $E_m, \phi, \vec{c}$ ) is discretized into linear array of  $10 \times 30 \times 768 \approx 2.3 \times 10^5$  voxels; **Cost of LLR computation is proportional to number of voxels**
- If no events of  $D$  fall within a voxel, it does not affect LLR

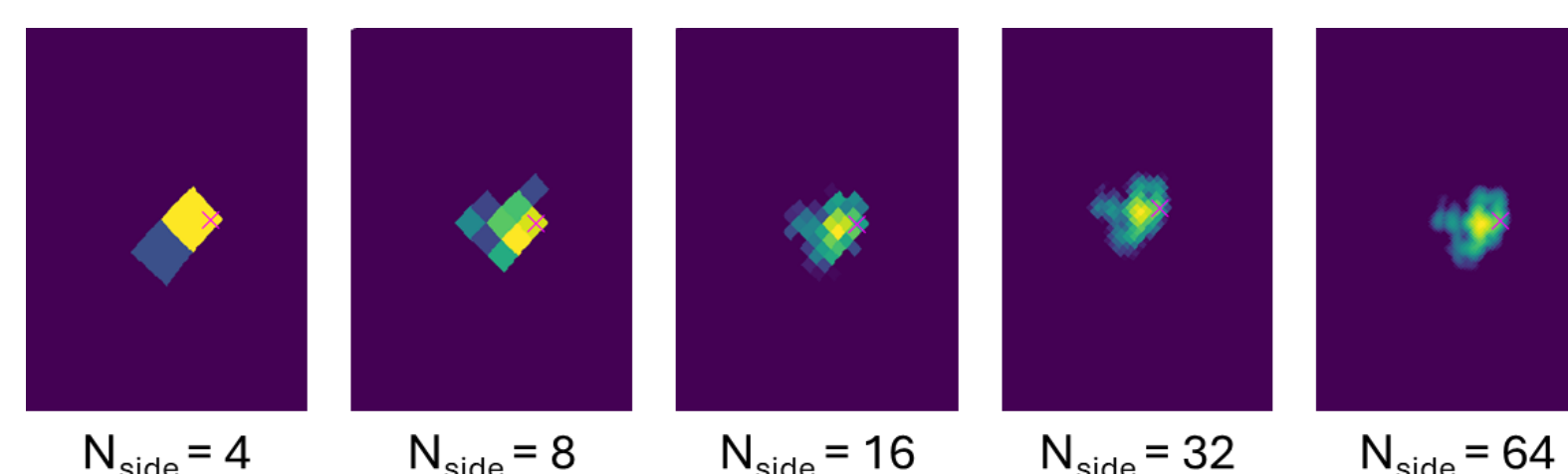


% Non-empty voxels for 16 transients from COSI Data Challenge 3

- Idea:** reduce  $R, B$  to **non-empty** voxels before mapping
- > 50x problem size reduction for all but brightest transients; does not require use of sparse matrices!**

### 2. Multi-Resolution Mapping

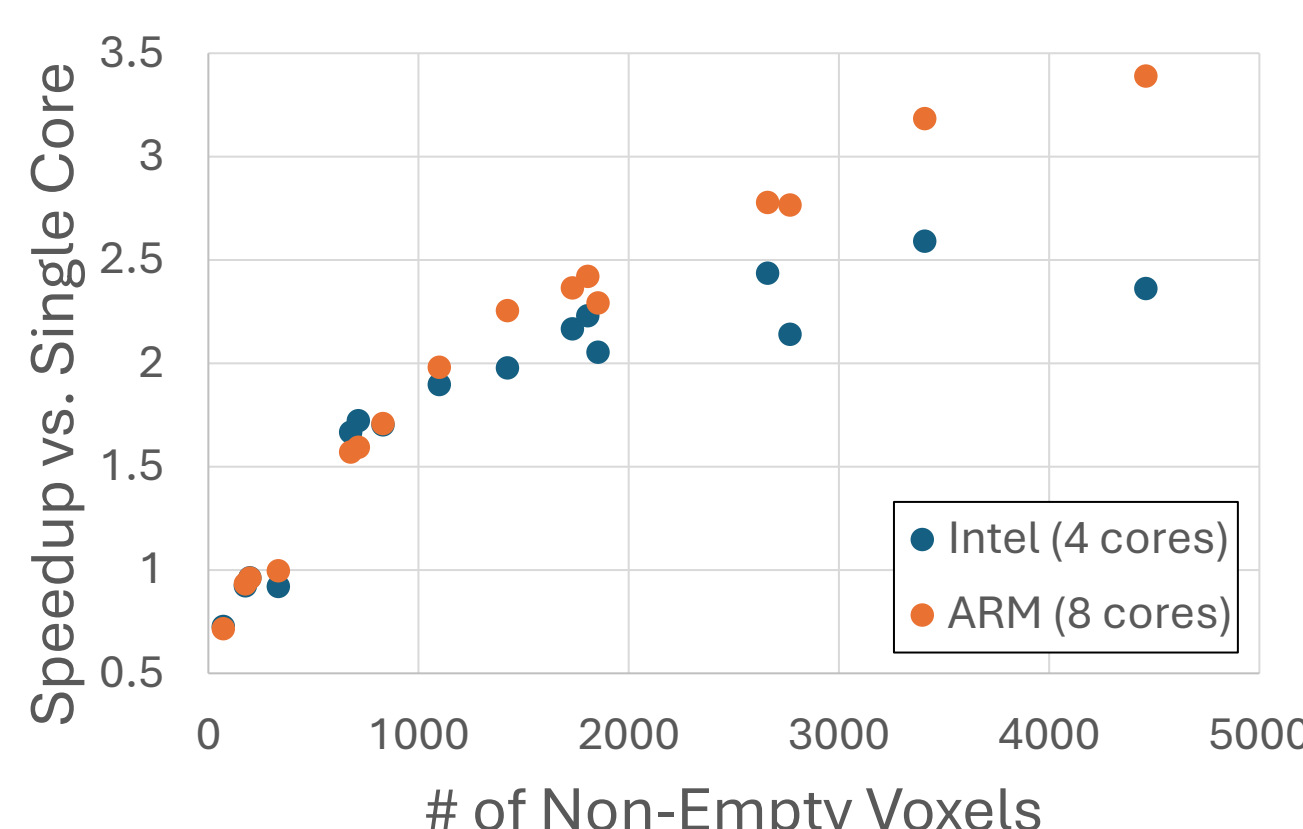
- Map is discretized into 49,152 pixels for  $\vec{s}$  using HEALPix [4] ( $N_{\text{side}} = 64, < 1^\circ$  resolution)
- Most pixels have **very low likelihood** relative to max
- Compute full map at  $N_{\text{side}} = 4$  (192 pixels), then refine **only** pixels in or near source's 90% containment region



- Iterative refinement increases resolution 4x each time
- Computes map detail near likely source, yet **eliminates 97-99% of computation** vs. full-resolution map

### 3. Parallelization

- Can parallelize LLR computation across map pixels  $\vec{s}$  and/or voxels of Compton data space
- Our implementation uses **Python**. "Natural" high-level parallelism in  $\vec{s}$  suffers from multi-process limitations
- Instead, parallelize only performance-critical loops via Numba JIT



- Some performance improvement (**2-3x** on 4-8 cores)
- Limited by small number of non-empty voxels for dimmer bursts, and by remaining sequential code
- Future:** recode in C++ to allow high-level multithreading

For more details, please see our proceedings paper at this link



## Validation

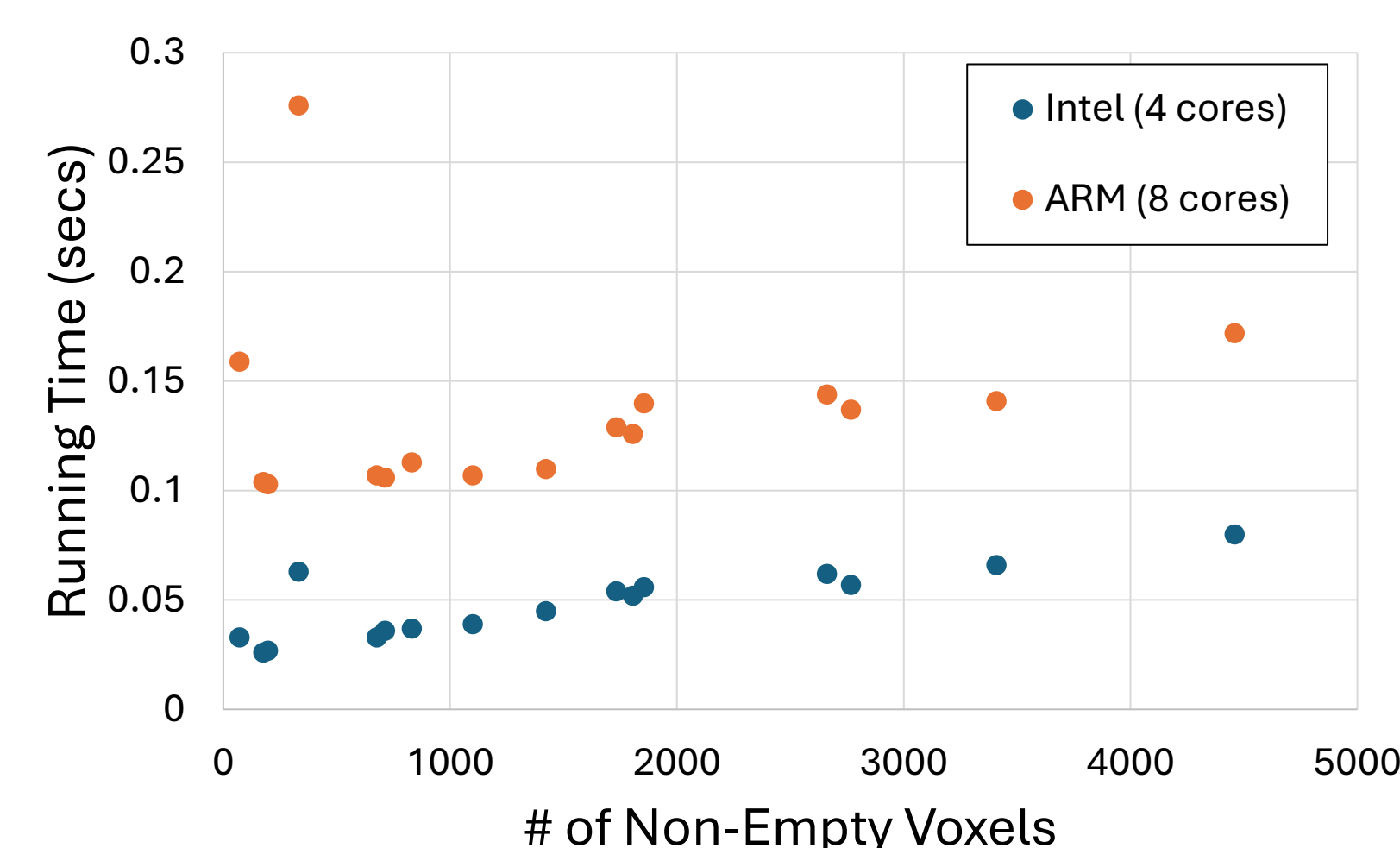
### Data and Telescope Model

- Tested on 17 simulated transients from **third COSI Data Challenge [1]** – published GRBs and MGFs
- Simulated observation by **Compton Spectrometer and Imager (COSI) [4]**, incl. source + LEO background
- Discretized response  $R$  is  $768 \times 10 \times 10 \times 30 \times 768$  (size in DRAM: 6.6 GiB)

### Computing Platforms

- Intel Core i7-13700TE – used aboard current and planned **balloon-borne** detectors
- ARM Cortex-A78AE – Nvidia Jetson Orin NX (**peak power < 10 W**); closer to **orbital** capability

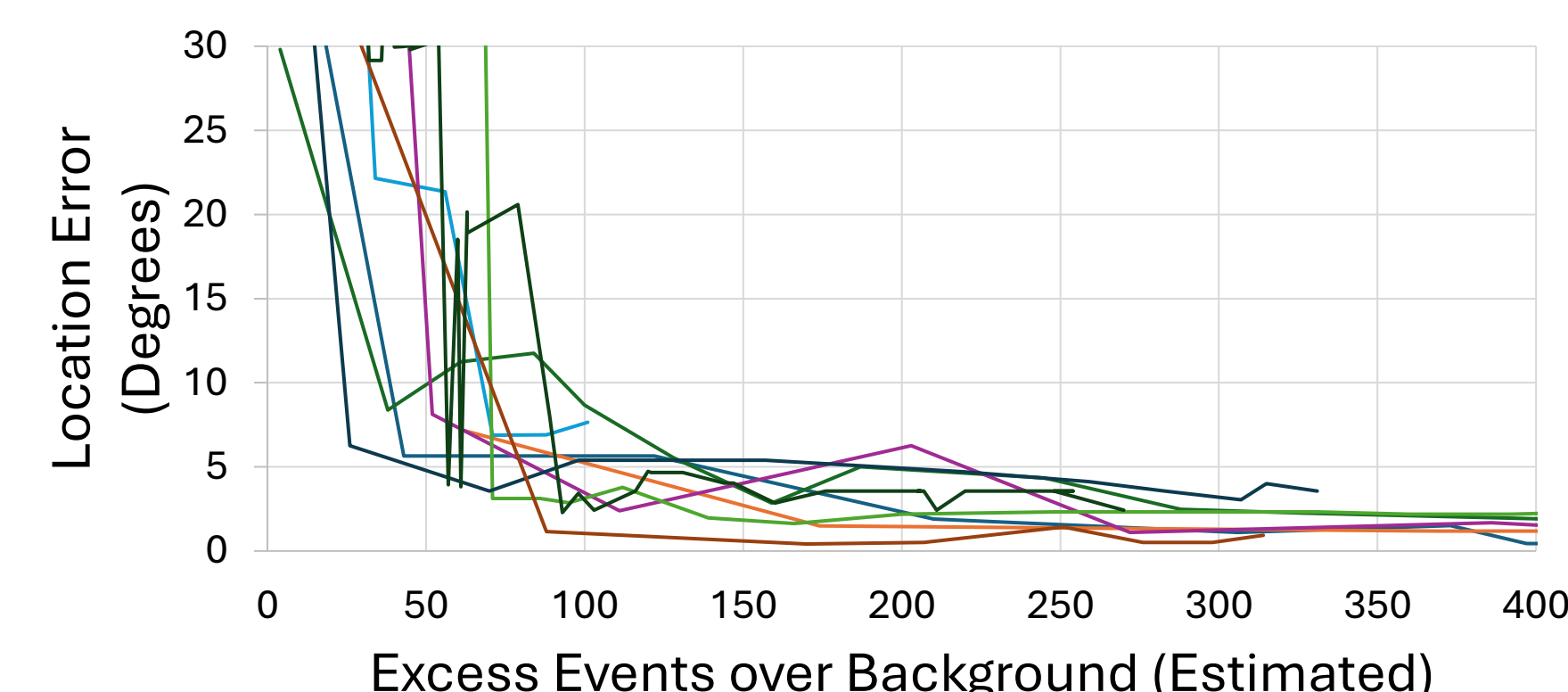
## Running Time



- 16 low- to moderate-brightness DC3 transients mapped in **< 300 ms** on ARM, **< 100 ms** on Intel
- One bright GRB, GBM090424592, w/over  $10^5$  events needed 513 ms on ARM (not shown in figure)

## Accuracy

- (Disclaimer: results reflect our analysis pipeline, not inherent resolution of COSI)**
- Measured angular distance from maximum-likelihood map pixel to true source location
- For 7 short transients ( $< 2$ s), mean accuracy was **2.28°**
- For 9 long transients, generated new map each second as events accumulated



After seeing  $\sim 150$  source events, typical accuracy was **within 5°**; final accuracy was **within 2°**

## Conclusion

- High-resolution source mapping is feasible in real time using low-power, on-board computing**
- Facilitates rapid coordination between observers*
- Key limitation:** resolution of instrument response  $R$
- More detailed response possible but will require alternate, less memory-intensive representation

## References

- [1] Compton Spectrometer and Imager (COSI) Collaboration, COSI Data Challenges, Apr., 2025.10.5281/zenodo.15126188.
- [2] K.M. Gorski et al., HEALPix: A framework for high-resolution discretization and fast analysis of data distributed on the sphere, *ApJ* 622 (2005) 759.
- [3] I. Martinez et al., The cosipy library: COSI's high-level analysis software, in *Proc. of 38th Int'l Cosmic Ray Conf.*, vol. 444, pp. 858:1–858:8, 2023.
- [4] J. Tomsick et al., The Compton Spectrometer and Imager, arXiv:2308.12362, 2023.